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SUPPLEMENT TO: A COMPUTER PROGRAM FOR  
THE DESIGN AND ANALYSIS OF LOW-SPEED  
AIRFOILS

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SUPPLEMENT TO: A COMPUTER PROGRAM FOR THE DESIGN AND ANALYSIS OF  
LOW-SPEED AIRFOILS

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SUMMARY

Three new options have been incorporated into an existing computer program for the design and analysis of low-speed airfoils. These options permit the analysis of airfoils having variable chord (variable geometry), a boundary-layer displacement iteration, and the analysis of the effect of single roughness elements. All three options are described in detail and are included in the FORTRAN IV computer program which is available through COSMIC.

INTRODUCTION

A conformal-mapping method for the design of airfoils with prescribed velocity-distribution characteristics, a panel method for the analysis of the potential flow about given airfoils, and a boundary-layer method have been combined. With this combined method, airfoils with prescribed boundary-layer characteristics can be designed and airfoils with prescribed shapes can be analyzed. All three methods and the FORTRAN IV computer program for the numerical evaluation of these methods are described in reference 1.

Three new options have been incorporated into the computer program described in reference 1. The previous version of the program (ref. 1) was capable of analyzing an airfoil with a simple flap. In the present version, an option has been added which allows the analysis of an airfoil having variable chord (variable geometry). The method of reference 1 did not contain a boundary-layer displacement iteration. An iteration procedure has been included in the present version. The third option to be added permits the analysis of the effect of single roughness elements. The input for all three options is described in detail.

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## SYMBOLS

Values are given in SI units.

$C_f$	boundary-layer skin-friction coefficient
$c$	airfoil chord, m
$C_d$	section profile-drag coefficient
$C_l$	section lift coefficient
$C_m$	section pitching-moment coefficient about quarter-chord point
$h$	height of roughness element normal to surface, m
$ls$	lower surface
$R$	Reynolds number based on free-stream conditions and airfoil chord
$R_h$	Reynolds number based on local conditions and height of roughness element
$U$	potential-flow velocity, m/s
$U_\infty$	free-stream velocity, m/s
$u_h$	x-component of velocity in turbulent boundary-layer at height of roughness element, m/s
$us$	upper surface
$v$	local velocity on airfoil, m/s
$x$	airfoil abscissa, m; axis in streamwise direction, tangential to surface
$x_R$	chord location of roughness element, m
$y$	airfoil ordinate, m
$\alpha$	angle of attack relative to zero-lift line, deg
$\Delta$	incremental change in quantity
$\delta_1$	boundary-layer displacement thickness, m
$\delta_2$	boundary-layer momentum thickness, m
$\nu$	kinematic viscosity, $m^2/s$



$\rho$  air density,  $\text{kg/m}^3$   
 $\tau_0$  shear stress at wall,  $\text{kg/m}\cdot\text{s}^2$

#### PROGRAM AVAILABILITY

The program is available at a nominal fee through the following organization:

Computer Software Management Information Center (COSMIC)  
112 Barrow Hall, University of Georgia  
Athens, Georgia 30602

Request the program by the designation PROFILE LAR-12727.

#### VARIABLE GEOMETRY

The previous version of the computer program (ref. 1) allowed the shape of an airfoil analyzed by the panel method to be altered so as to correspond to the deflection of a simple flap. Thus, that version only permitted the rotation of a portion of the airfoil, the flap, about a specified hinge point. Chord-increasing flaps were not allowed. The present version of the program can analyze this form of variable geometry. It should be noted that, while the airfoil shape which results from the exercise of this option does have an increased chord, it does not contain a slot and, thus, is still a single-element as opposed to a multi-element airfoil. An application of this capability is described in reference 2.

#### FLAP Card

The variable-geometry option is selected by setting  $\text{NUPU} = 1, 2, 3,$  or  $4$  on the FLAP card.

$\text{NUPA}, \text{NUPE},$  and  $\text{NUPI}$  are neglected.

$\text{NUPU} = 1$  - The F-words specify the points to be deleted. The five digits of  $F_i$  are denoted  $\text{aaabb}$ . Points  $\text{aaa}$  through  $\text{aaa} + \text{bb}$  are deleted. If  $\text{bb} = 00$ , only point  $\text{aaa}$  is deleted.

It is recommended that the F-words be specified with decreasing values of  $\text{aaa}$  as the points after point  $\text{aaa}$  (higher point number) are renumbered. This means that  $\text{aaa}$  for  $F_1$  should be greater than  $\text{aaa}$  for  $F_2$  which should be greater than  $\text{aaa}$  for  $F_3$  and so on.

Only one FLAP card with  $\text{NUPU} = 1$  is allowed.

NUPU = 2 - The F-words specify points to be added to the upper surface. The new points are added after the point on the upper surface having the greatest  $x/c$  remaining after the deletions which resulted from the FLAP card with NUPU = 1. Thus, if point 1 ( $x/c = 1$ ) was not deleted, only points with  $x/c > 1$  can be added.

$$0.01F_1 = x_1/c \quad [F5.4]$$

$$0.01F_2 = y_1/c \quad [F5.4]$$

$(F_3, F_4) = (x_2/c, y_2/c)$  and so on

It should be noted that the new points must be in order of increasing  $x/c$ .

NUPU = 3 - The F-words specify points to be added to the lower surface. The F-words are interpreted just as they are for a FLAP card with NUPU = 2.

NUPU = 4 - The F-words specify additional points to be splined in between the points available so far. The F-words are interpreted just as they are for an FXPR card. (See ref. 1, p. 45.)

It should be remembered that the points are renumbered during the execution of each of the preceding FLAP cards.

The panel method is called automatically after a FLAP card with NUPU = 4 is read. Following this card, any other cards (in the proper sequence, of course) are allowed except another FLAP card. Only airfoil coordinates generated in the design mode or read in following an FXPR card can be altered by FLAP cards with NUPU = 1, 2, 3, and 4. Thus, a FLAP card with NUPU = 1, 2, 3, or 4 cannot follow another FLAP card.

#### Example

The following card sequence illustrates the use of the variable-geometry option.

```

TPA1  664 1250 400 1450 000 1650 300 1850 400 2050 500 2250 600 2450 700
TPA1  664 2650 900 2940 900 3030 1020 000 1300 3350 100 3550 200 4350 300
TRA1  664 4550 200 4750 100 4950 000 5150 2500 6000 400
TRA2  664 400 1250 200 1000 720 400 850 200 300 710 100 300 000 000
ALFA  1 1 000
DIAG  1
FLAP  1 5209 700 500 201
FLAP  211000 -35012000 -900
FLAP  3 8400 -245 9600 -29010200 -49012000 -900
FLAP  4524005120050200492000220001300
ALFA  1 1 000
DIAG  2
ENDE

```

The first FLAP card deletes points 52 through 61 as well as points 7, 5, 3, and 2 (in the x-y-v listing, N = 51 through 60, 6, 4, 2, and 1). If the chord is to be increased, some of the points near the trailing edge should be deleted. In other words, a short distance between points is required near the new trailing edge, not the old one. The second FLAP card specifies two points for the extension of the upper surface: ( $x/c = 1.1000, y/c = -0.0350$ ) and ( $x/c = 1.2000, y/c = -0.0900$ ). The third FLAP card specifies four points for the extension of the lower surface: ( $x/c = 0.8400, y/c = -0.0265$ ), ( $x/c = 0.9600, y/c = -0.0290$ ), ( $x/c = 1.0800, y/c = -0.0490$ ), and ( $x/c = 1.2000, y/c = -0.0900$ ). The fourth FLAP card inserts in the equiangular-spacing mode (ref. 1) four points between points 52 and 53, two points between points 51 and 52, two points between points 50 and 51, two points between points 49 and 50, two points between points 2 and 3, and three points between points 1 and 2. The panel method is called automatically after the fourth FLAP card.

This card sequence plots into one diagram (fig. 1) the velocity distributions for airfoil 664 with and without the variable-geometry flap extension. Two velocity distributions, each at  $\alpha = 0^\circ$  relative to the chord line, are plotted. The following x-y-v listings are also generated.

AIRFOIL	664	16.632	0.00	
N	X	Y	VELOCITY DISTRIBUTIONS FOR THE ABOVE ANGLES OF ATTACK RELATIVE TO THE CHORD LINE	
0	1.00000	0.00000	.773	
1	.99623	.00092	.799	
2	.98557	.00391	.862	
3	.96923	.00881	.934	
4	.94774	.01461	.978	
5	.92110	.02193	.997	
6	.88964	.03005	1.020	
7	.85407	.03927	1.048	
8	.81512	.04942	1.081	
9	.77353	.06020	1.121	
10	.73008	.07122	1.167	
11	.68549	.08197	1.220	
12	.64043	.09167	1.281	
13	.59497	.09937	1.318	
14	.54869	.10482	1.326	
15	.50167	.10940	1.331	
16	.45437	.11029	1.334	
17	.40727	.11060	1.335	
18	.36097	.10939	1.335	
19	.31564	.10679	1.334	
20	.27205	.10262	1.330	
21	.23051	.09720	1.324	
22	.19145	.09055	1.315	
23	.15521	.08277	1.301	
24	.12216	.07401	1.281	
25	.09258	.06441	1.252	
26	.06674	.05416	1.211	
27	.04487	.04348	1.150	
28	.02714	.03261	1.058	
29	.01371	.02183	.909	
30	.00468	.01155	.661	
31	.00023	.00229	.197	
32	.00146	-.00521	.562	
33	.00903	-.01173	.842	
34	.02234	-.01817	.954	
35	.04097	-.02423	1.004	
36	.06471	-.02979	1.028	
37	.09334	-.03482	1.039	
38	.12651	-.03936	1.046	
39	.16380	-.04341	1.052	
40	.20474	-.04693	1.057	
41	.24882	-.04990	1.060	
42	.29552	-.05229	1.064	
43	.34429	-.05406	1.066	

AIRFOIL	664	16.63X	0.00	
N	X	Y	VELOCITY	DISTRIBUTIONS FOR THE ABOVE ANGLES OF ATTACK RELATIVE TO THE CHORD LINE
44	.39452	-.05522	1.070	
45	.44556	-.05572	1.074	
46	.49678	-.05546	1.079	
47	.54754	-.05433	1.084	
48	.59719	-.05219	1.090	
49	.64512	-.04967	1.096	
50	.69117	-.04322	1.076	
51	.73561	-.03567	1.036	
52	.77909	-.02623	.957	
53	.82219	-.01537	.875	
54	.86399	-.00603	.823	
55	.90260	-.00224	.787	
56	.93641	.00102	.761	
57	.96395	.00198	.751	
58	.98400	.00142	.757	
59	.99602	.00045	.767	
60	1.00000	-.00000	.773	

ALPHA = 3.85 DEGREES CMO = -.0909 ETA = 1.131

VARIABLE GEOMETRY AIRFOIL 664  
 DELETED POINTS 52 THROUGH 61  
 DELETED POINT 7  
 DELETED POINT 5  
 DELETED POINTS 2 THROUGH 3  
 INSERTED POINT ON UPPER SURFACE AT X/C = 1.1000 Y/C = -.0350  
 INSERTED POINT ON UPPER SURFACE AT X/C = 1.2000 Y/C = -.0900  
 INSERTED POINT ON LOWER SURFACE AT X/C = .8400 Y/C = -.0265  
 INSERTED POINT ON LOWER SURFACE AT X/C = .9600 Y/C = -.0290  
 INSERTED POINT ON LOWER SURFACE AT X/C = 1.0000 Y/C = -.0490  
 INSERTED POINT ON LOWER SURFACE AT X/C = 1.2000 Y/C = -.0900

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PANEL METHOD AIRFOIL 664 CA = 1.58921, 6.78770 ALPHA = 13.10 DEGREES  
 AIRFOIL 664 16.63% THICKNESS 0.00% FLAP 0.00 DEGREES DEFLECTION

N	X	Y	VELOCITY DISTRIBUTIONS FOR THE ABOVE ANGLES OF ATTACK RELATIVE TO THE CHORD LINE
0	1.20000	-.09000	.819
1	1.19373	-.08620	.920
2	1.17500	-.07496	1.021
3	1.14791	-.05708	1.137
4	1.10000	-.03500	1.261
5	1.07054	-.02294	1.290
6	1.03709	-.01132	1.294
7	1.00000	0.00000	1.285
8	.96923	.00381	1.286
9	.92110	.02193	1.294
10	.85407	.03927	1.303
11	.71512	.04942	1.326
12	.77353	.06020	1.359
13	.73008	.07122	1.401
14	.68549	.08197	1.455
15	.64043	.09167	1.516
16	.59497	.09937	1.554
17	.54869	.10482	1.563
18	.50167	.10840	1.568
19	.45437	.11029	1.572
20	.40727	.11060	1.577
21	.36097	.10938	1.562
22	.31564	.10670	1.589
23	.27205	.10262	1.596
24	.23051	.09720	1.605
25	.19145	.09055	1.614
26	.15521	.08277	1.623
27	.12216	.07401	1.633
28	.09258	.06441	1.643
29	.06674	.05416	1.652
30	.04487	.04348	1.661
31	.02714	.03261	1.663
32	.01371	.02183	1.661
33	.00468	.01155	1.612
34	.00023	.00229	1.553
35	.00146	-.00521	.853
36	.00903	-.01173	.072
37	.02234	-.01817	.283
38	.04097	-.02423	.479
39	.06471	-.02979	.597
40	.09334	-.03482	.671
41	.12651	-.03936	.722

AIRFOIL	664	16.63% THICKNESS	0.00% FLAP	0.00 DEGREE DEFLECTION
N	X	Y	VELOCITY DISTRIBUTIONS FOR THE ABOVE ANGLES OF ATTACK RELATIVE TO THE CHORD LINE	
42	.16390	-.04341	.759	
43	.20474	-.04693	.787	
44	.24882	-.04990	.808	
45	.29552	-.05229	.824	
46	.34429	-.05406	.835	
47	.39452	-.05522	.844	
48	.44556	-.05572	.850	
49	.49679	-.05546	.855	
50	.54754	-.05433	.856	
51	.59719	-.05219	.854	
52	.64512	-.04867	.846	
53	.69117	-.04322	.801	
54	.74184	-.03641	.747	
55	.79192	-.03041	.700	
56	.84000	-.02650	.666	
57	.88180	-.02542	.653	
58	.92188	-.02639	.645	
59	.96000	-.02900	.647	
60	1.00411	-.03401	.644	
61	1.04421	-.04078	.647	
62	1.08000	-.04900	.660	
63	1.12280	-.06177	.698	
64	1.15631	-.07351	.736	
65	1.18047	-.08254	.757	
66	1.19510	-.08812	.774	
67	1.20000	-.09000	.819	

## BOUNDARY-LAYER DISPLACEMENT ITERATION

The theoretical results for  $c_l$  versus  $c_d$  from the previous version of the computer program (ref. 1) agree remarkably well with experimental measurements. (For example, see ref. 3.) This good agreement, however, does not hold for  $c_l$  versus  $\alpha$  or  $c_m$  versus  $\alpha$ , particularly for aft-loaded airfoils. This is not surprising in that the boundary-layer displacement effect was only accounted for by reducing the lift-curve slope from its theoretical value to  $2\pi$ . An improvement could therefore be expected from a more detailed analysis of the displacement effect.

There exists, however, a fundamental flaw in the philosophy of the application of displacement iterations. All displacement effects are of second order in boundary-layer theory (ref. 4). Accordingly, it is inconsistent to include the displacement effect while neglecting other pertinent second-order effects which arise from the pressure gradient normal to the surface within the boundary layer and other  $y$ -component terms in the Navier-Stokes equations. This flaw becomes more significant as the boundary-layer thickness increases.

At the trailing edge, difficult problems arise. The potential-flow solution yields steep pressure gradients toward the trailing edge which result in a very high slope for the displacement thickness. This high slope can result in a rapid divergence for the displacement iteration, even for high Reynolds numbers. The order (quality) of the trailing-edge treatment has a significant influence on the results. The wake solution incorporated in the present panel method gives very precise results for the lift coefficients of airfoils with blunt trailing edges. It, however, also predicts steep pressure gradients toward the trailing edge which, in turn, accelerate the divergence of the displacement iteration. Moreover, this solution also clearly shows that the small region which surrounds the trailing edge has a great influence on the solution for the entire airfoil.

One solution to this divergence problem is to artificially smooth the boundary-layer displacement after each iteration. But, even if convergence is obtained and, furthermore, even if smoothing were not required for convergence, the iteration process would still be questionable due to the neglect of the second-order boundary-layer terms previously mentioned. A wake solution which minimizes the pressure gradients near the trailing edge could improve the iteration process but would not eliminate the fundamental flaw in philosophy.



The question remains as to what simple procedures can be developed to obtain at least a rough estimate of the displacement effect. As previously explained, multiple iterations are not logical. Accordingly, in the present method, only one iteration is performed. The displacement thickness is smoothed once and then added to the airfoil contour. The lift and pitching-moment coefficients are then computed for the new contour and stored. Later the linear portions of the  $c_l - \alpha$  and  $c_m - \alpha$  curves are adjusted by a least-squares fit to these stored values. The separation corrections are then applied as discussed in reference 1. Thus, only a few angles of attack require this displacement iteration. The remaining angles of attack are adjusted according to the least-squares fit. The displacement effect is considered to be linear in  $\alpha$ . A higher-order effect cannot be expected from such a simple approach.

This simple procedure does not require much computing time. The results, of course, depend on the smoothing process. In the present version of the program, the curvature of  $\delta_1(x)$  (i.e.,  $\frac{d^2\delta_1}{dx^2}$ ) is limited. The limit can be specified in the input. This limit (SLM) is preset to  $\frac{1}{2} \frac{d^2\delta_1}{dx^2} < 0.5$  ( $\equiv$  SLM).

The single iteration is initiated by one input card, which must immediately precede an input card which initiates a boundary-layer computation (i.e., an RE, FLZW, or PLW card).

#### DPIT Card

NUPA, NUPE, NUPI, and NUPU are neglected.

The F-words specify the angles of attack for which a displacement iteration is performed and also the plot mode mbt. The five digits of  $F_i$  are denoted abcde. The variable abc is interpreted as an integer  $n$  and a displacement iteration is initiated for the  $n$ th angle of attack on the preceding ALFA card. A displacement iteration is performed for each Reynolds number from the immediately following RE, FLZW, or PLW card. The variable d determines the plot mode. If  $d > 0$ , a diagram containing the airfoil contour (including the displacement thickness) and the velocity distribution for the angle of attack under consideration is plotted after each displacement iteration. The plot mode mbt is set equal to  $d - 1$  and is described under "DIAG Card" in reference 1 (p. 52) and reviewed below.

$d = 1$  — Axes are drawn, one set of data is plotted, and the diagram is terminated (i.e., closed to further plotting).

$d = 2$  — Axes are drawn, one set of data is plotted, and the diagram is open to further plotting.

d = 3 – No axes are drawn and one set of data is plotted into the existing diagram which is then terminated.

d = 4 – No axes are drawn and one set of data is plotted into the existing diagram which remains open to further plotting.

If d = 2 or 3, the RE , FLZW, or PLW card must specify only one Reynolds number.

Up to five F-words are allowed which means that displacement iterations can be performed for up to five angles of attack.

If  $F_5 < 0$ , the limit for  $\frac{d^2\delta_1}{dx^2}$  is set to SLM = -0.bcde. This new

limit is used until it is reset by another DPIT card with  $F_5 < 0$ . Obviously, only four angles of attack can be specified on DPIT cards with  $F_5 < 0$ .

### Examples

The following card sequences illustrate some of the DPIT-card options.

```
TRA1 0315 1650 400 1750 100 1350 400 2050 410 2250 430 2450 470 2650 550
TRA1 0315 2850 710 3050 1030 000 1670 3250 30 3450 70 3650 90 3850 100
TRA1 0315 4050 85 4250 55 4450 -05 4650 -125 4850 -265 6000 100
TRA2 0315 400 1650 200 400 770 600 1150 200 300 650 300 300 000 000
ALFA 10 000 100 200 300 400 500 600 700 800 900
DIAG
DPIT 110 510 910
RE 03 200003 6000
CDCL
ENDE
```

After the RE card is read, displacement iterations for the first, fifth, and ninth angles of attack (i.e.,  $\alpha = 0^\circ, 4^\circ,$  and  $8^\circ$  relative to the zero-lift line) are performed for both  $R = 2 \times 10^6$  and  $R = 6 \times 10^6$ . A diagram is plotted for each displacement iteration. A potential-flow diagram (no displacement iteration) is also plotted (DIAG card). Thus, one diagram containing 10 velocity distributions (DIAG card) (fig. 2) and six diagrams containing one velocity distribution each (DPIT card) (fig. 3) are plotted. The  $c_l - \alpha$  and  $c_m - \alpha$  portions of the boundary-layer summary and its plot (CDCL card) are adjusted according to the computed displacement effect.

It should be noted that each displacement iteration requires a solution from the panel method. Thus, for an airfoil having 61 points, each displacement iteration requires approximately 8 seconds CPU time on a Control Data 6600 computer.

```

TRA1 0215 1650 400 1750 100 1850 400 2050 410 2250 420 2450 470 2650 550
TRA1 0215 2250 710 3050 1030 000 1670 3250 30 2450 70 3650 90 3850 100
TRA1 0215 4050 35 4250 55 4450 -05 4650 -125 4950 -365 6000 100
TRA2 0315 400 1650 200 400 770 600 1150 200 300 650 300 300 000 000
ALFA 3 300 700
DIAG 1
ALFA 10 000 100 200 300 400 500 600 700 800 900
DPIT 440 930
RE 03 6000
CDCL
ENDE

```

The preceding card sequence plots one diagram (fig. 4) which contains both potential-flow and displacement-iteration shapes and velocity distributions for  $\alpha = 3^\circ$  and  $7^\circ$ . Note that only one Reynolds number is considered and that displacement iterations are only performed for  $\alpha = 3^\circ$  and  $7^\circ$ . The boundary-layer summary which follows contains the adjustments due to the computed displacement effect. AC is the adjusted angle of attack (relative to the zero-lift line).

SUMMARY AIRFOIL 315 ANGLE OF ATTACK RELATIVE TO THE ZERO-LIFT LINE ALPHA = 2.95 DEGREES  
 \* INDICATES VELOCITY REDUCTION WITHIN BUBBLE BELOW .94

R = 6000000 MU = 3

ALPHA = 0.00 DEGREES  
 1 S TURB S SEP CD  
 UPPER .5749 0.0000 .0030  
 LOWER .4107 0.0000 .0017  
 TOTAL CL = 0.000 CD = .0047  
 CM = -.0662 AC = .18

ALPHA = 1.00 DEGREES  
 1 S TURB S SEP CD  
 UPPER .5676 0.0000 .0032  
 LOWER .4086 0.0000 .0016  
 TOTAL CL = .110 CD = .0048  
 CM = -.0682 AC = 1.11

ALPHA = 2.00 DEGREES  
 1 S TURB S SEP CD  
 UPPER .5980 0.0000 .0034  
 LOWER .4069 0.0000 .0015  
 TOTAL CL = .220 CD = .0049  
 CM = -.0702 AC = 2.05

ALPHA = 3.00 DEGREES  
 1 S TURB S SEP CD  
 UPPER .4067 0.0000 .0036  
 LOWER .4052 0.0000 .0015  
 TOTAL CL = .330 CD = .0050  
 CM = -.0722 AC = 2.98

ALPHA = 4.00 DEGREES  
 1 S TURB S SEP CD  
 UPPER .6147 0.0000 .0038  
 LOWER .4036 0.0000 .0014  
 TOTAL CL = .440 CD = .0052  
 CM = -.0742 AC = 3.91

ALPHA = 5.00 DEGREES  
 1 S TURB S SEP CD  
 UPPER .6569 0.0000 .0042  
 LOWER .4022 0.0000 .0013  
 TOTAL CL = .550 CD = .0056  
 CM = -.0762 AC = 4.85

SUMMARY AIRFOIL 315 ANGLE OF ATTACK RELATIVE TO THE ZERO-LIFT LINE ALPHA0 = 2.95 DEGREES  
\* INDICATES VELOCITY REDUCTION WITHIN BUBBLE BELOW .94

R = 600000 MU = 3

ALPHA = 6.00 DEGREES  
1 S TURB S SEP CD  
UPPER .7525 0.0000 .0051  
LOWER .4007 0.0000 .0013  
TOTAL CL = .660 CD = .0064  
CM = -.0782 AC = 5.78

ALPHA = 7.00 DEGREES  
1 S TURB S SEP CD  
UPPER .8430 .0006 .0053  
LOWER .3992 0.0000 .0012  
TOTAL CL = .769 CD = .0075  
CM = -.0801 AC = 6.71

ALPHA = 8.00 DEGREES  
1 S TURB S SEP CD  
UPPER .9073 .0036 .0074  
LOWER .3978 0.0000 .0012  
TOTAL CL = .876 CD = .0086  
CM = -.0813 AC = 7.64

ALPHA = 9.00 DEGREES  
1 S TURB S SEP CD  
UPPER .9467 .0071 .0085  
LOWER .3962 0.0000 .0011  
TOTAL CL = .982 CD = .0096  
CM = -.0823 AC = 8.58

## SINGLE ROUGHNESS ELEMENTS

Recent flight and wind-tunnel experiments indicate that single roughness elements such as flap and aileron hinges and poorly faired spoilers significantly degrade the overall performance of an airplane (ref. 5). With the previous version of the program (ref. 1), only the effect of roughness on boundary-layer transition could be considered. Fixed transition points could be specified using transition mode 1 or 2, whereas premature transition due to distributed roughness or free-stream turbulence could be analyzed using transition modes greater than 3. (See "RE Card," ref. 1, p. 56.)

In the present version of the program, an option has been added which allows the analysis of the effect of single roughness elements on a turbulent as well as a laminar boundary layer. The method is described in detail in reference 5 and reviewed below.

The increase  $\Delta\delta_2$  of the boundary-layer momentum thickness  $\delta_2$  due to a single roughness element of height  $h$  is assumed to depend only on the local roughness Reynolds number  $R_h = \frac{u_h h}{\nu}$  where  $u_h$  is the x-component of the velocity in the turbulent boundary layer at a distance  $h$  from the surface. For a turbulent boundary layer, the increase of  $\delta_2$  due to the roughness element is assumed to be

$$\frac{\Delta\delta_2}{c} = 0.15 \frac{u_h}{U_\infty} \frac{h}{c}$$

where  $c$  is the airfoil chord and  $U_\infty$  is the free-stream velocity. An expression for the velocity  $u_h$  is taken from reference 6 and transformed to the variables available in the boundary-layer method. This yields

$$\frac{u_h}{U} = \sqrt{C_f} \left[ 2.17 \ln \left( \sqrt{C_f} \frac{U}{U_\infty} R \frac{h}{c} \right) + 6.5 \right]$$

where  $U$  is the local potential-flow velocity,  $C_f \left( = \frac{\tau_0}{\rho U^2} \right)$  is the local skin-friction coefficient, and  $R \left( = \frac{U_\infty c}{\nu} \right)$  is the Reynolds number based on free-stream conditions and airfoil chord. In the skin-friction coefficient,  $\tau_0$  is the shear stress at the wall and  $\rho$  is the air density.

If the boundary layer is laminar at the position of the roughness element, transition is assumed to occur at that position. This is specified as  $h = 0$  which acts as a "latest" transition point. Upstream of that position, any transition mode except 1 or 2 (fixed transition) is allowed. This approach is more logical for many analyses than fixed transition, in front of which no other transition criterion is applied except transition following laminar separation. Fixed transition (mode 1 or 2) alone could result in delayed transition at some (high) angles of attack - an effect which is obviously not intended.

### RE Card

F-words 11-14 contain the data for single roughness elements. These words previously only contained the transition points for transition modes 1 and 2 (fixed transition).

If  $F_{14} < 0$ , F-words 11-14 specify single roughness elements and, therefore, transition modes 1 and 2 cannot be used. The five digits of  $F_{11} - F_{14}$  are denoted  $abbcc$ . For  $F_{11} - F_{13}$ ,  $a$  is either a blank or 0. For  $F_{14}$ ,  $a$  is a minus sign (-). The digits  $bb$  specify the location of the roughness element  $x_R$  in percent chord. The digits  $cc$  which are read as  $0.cc$  specify the roughness height  $h$  in percent chord. Thus, roughness heights can be specified over the range  $0.0001 \leq h/c \leq 0.0099$ .  $F_{11}$  and  $F_{12}$  specify roughness elements on the upper surface whereas  $F_{13}$  and  $F_{14}$  are for the lower surface. If  $x_R = 0$  is specified, no roughness element is introduced for that F-word. Thus, 0, 1, or 2 roughness elements can be specified on each surface.

$F_{11} - F_{14}$  are read from each RE card which specifies at least one Reynolds number. The roughness elements remain in effect until an RE card with  $F_2 \neq 0$  is read.

Roughness elements can only be analyzed at positions which are actual airfoil coordinates. If  $x_R$  is specified at an  $x/c$  which does not correspond to any of the airfoil coordinates, the roughness-element location is shifted to the next airfoil coordinate downstream of  $x_R$ . If there is no airfoil coordinate close enough to the desired roughness-element location, one can be inserted using a PAN or FXPR card. (See ref. 1.)

### Examples

The following RE card specifies two roughness elements on the upper surface at  $x/c = 0.60$  and  $x/c = 0.80$ , each with a height  $h/c = 0.0010$ , and one roughness element on the lower surface at  $x/c = 0.70$ , with a height  $h/c = 0.0015$ .

```

RE      03      4000                                     6010 8010 0000-7015

```

The following RE card specifies the same roughness elements on the upper surface and none on the lower surface.

RE            03    4000    6010 8010 0000-0001





#### REFERENCES

1. Eppler, Richard; and Somers, Dan M.: A Computer Program for the Design and Analysis of Low-Speed Airfoils. NASA TM-80210, 1980.
2. Eppler, Richard: Some New Airfoils. Science and Technology of Low Speed and Motorless Flight, NASA CP-2085, Part 1, 1979, pp. 131-153.
3. Eppler, Richard; and Somers, Dan M.: Low Speed Airfoil Design and Analysis. Advanced Technology Airfoil Research - Volume I, NASA CP-2045, Part 1, 1979, pp. 73-99.
4. Van Dyke, Milton: Perturbation Methods in Fluid Mechanics. Applied Mathematics and Mechanics, F. N. Frenkiel and G. Temple, eds., Academic Press, Inc., 1964, pp. 132-134.
5. Eppler, Richard: The Effect of Disturbances on a Wing. Science and Technology of Low Speed and Motorless Flight, NASA CP-2085, Part 1, 1979, pp. 81-91.
6. Ludwig, H.; and Tillman, W.: Investigations of the Wall-Shearing Stress in Turbulent Boundary Layers. Ingenieur-Archiv, vol. 17, no. 4, 1949, pp. 288-299.



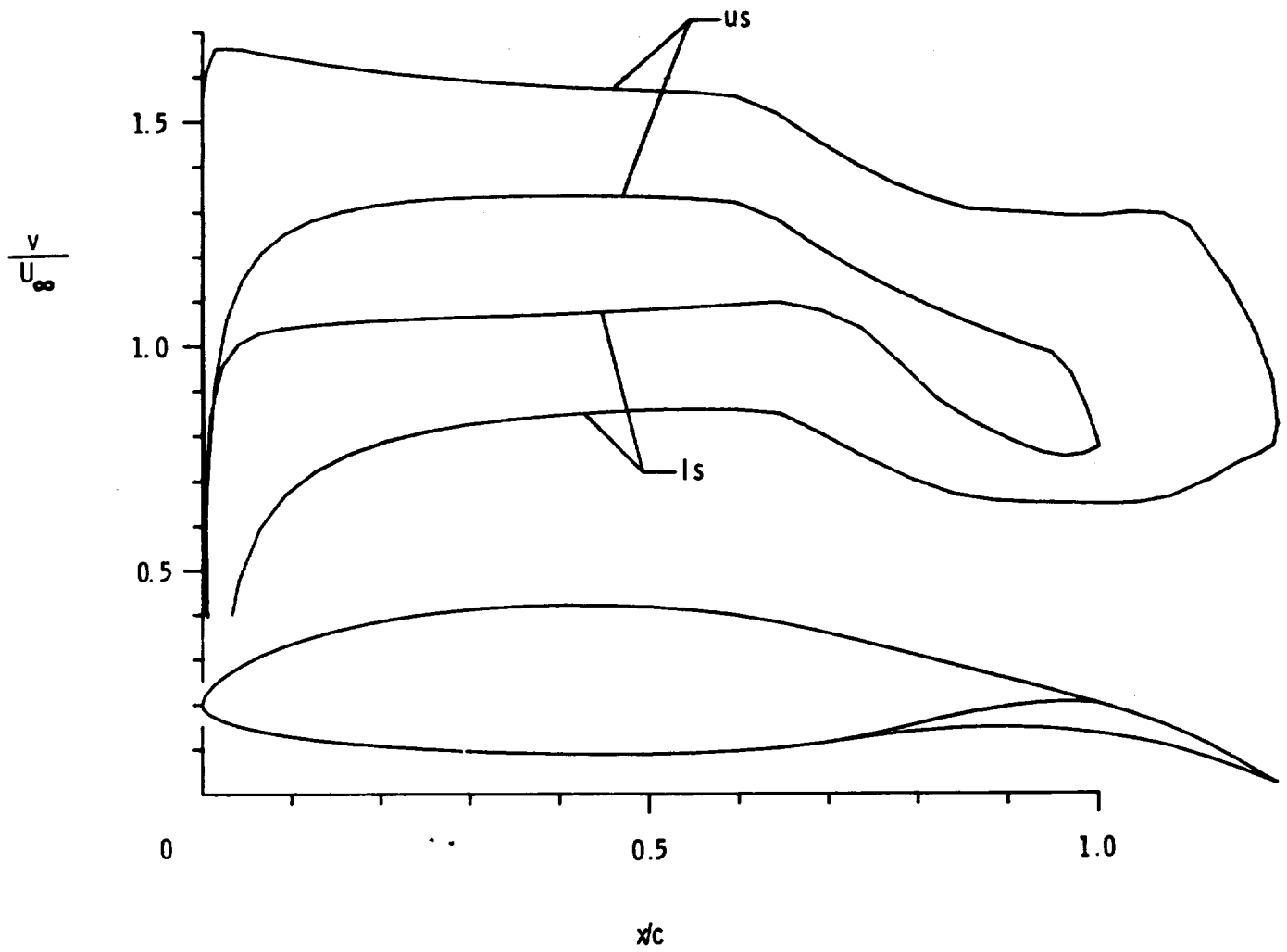


Figure 1.- Variable geometry. (Airfoil 664;  $\alpha = 0^\circ$  relative to chord line)

20

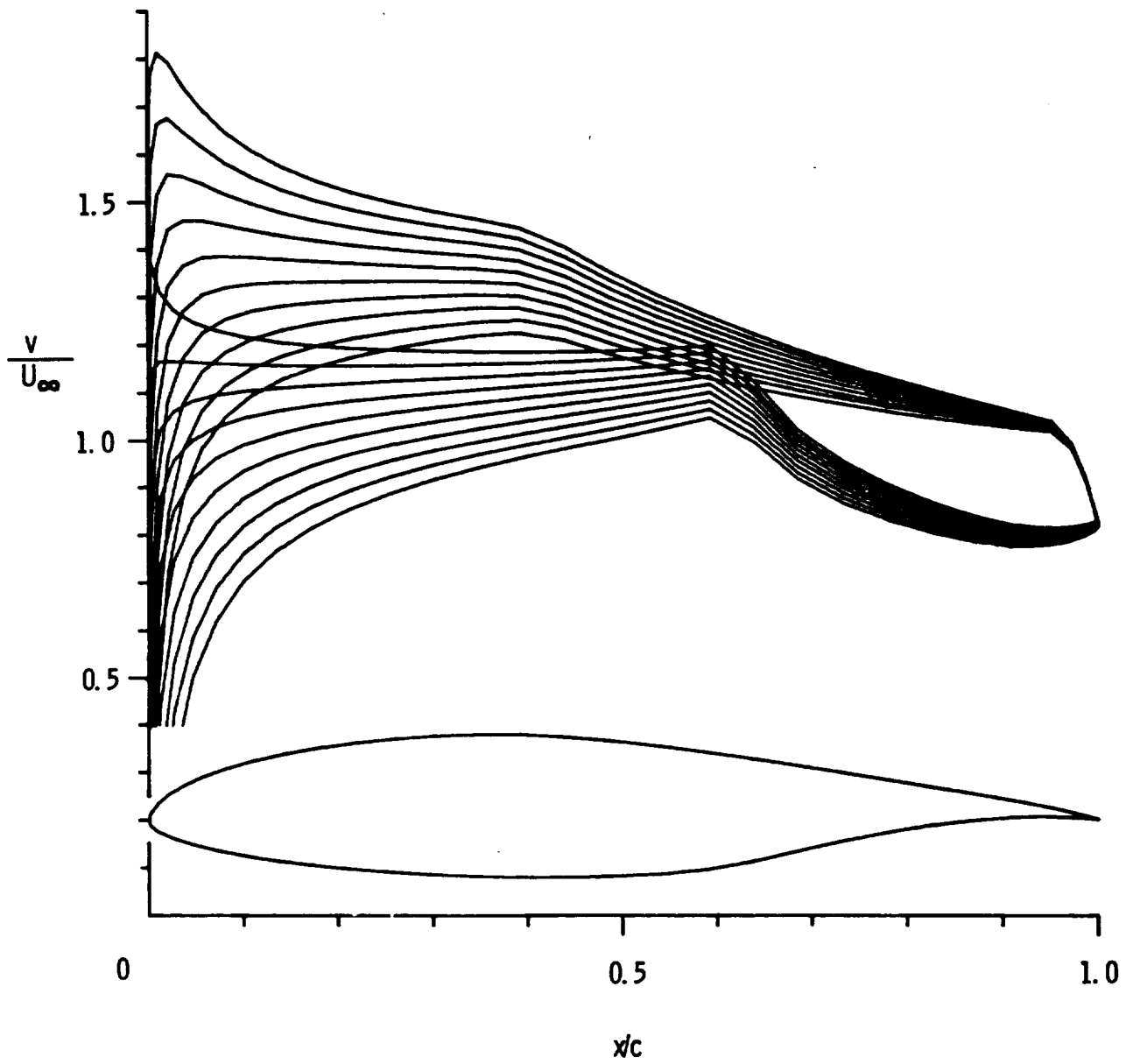
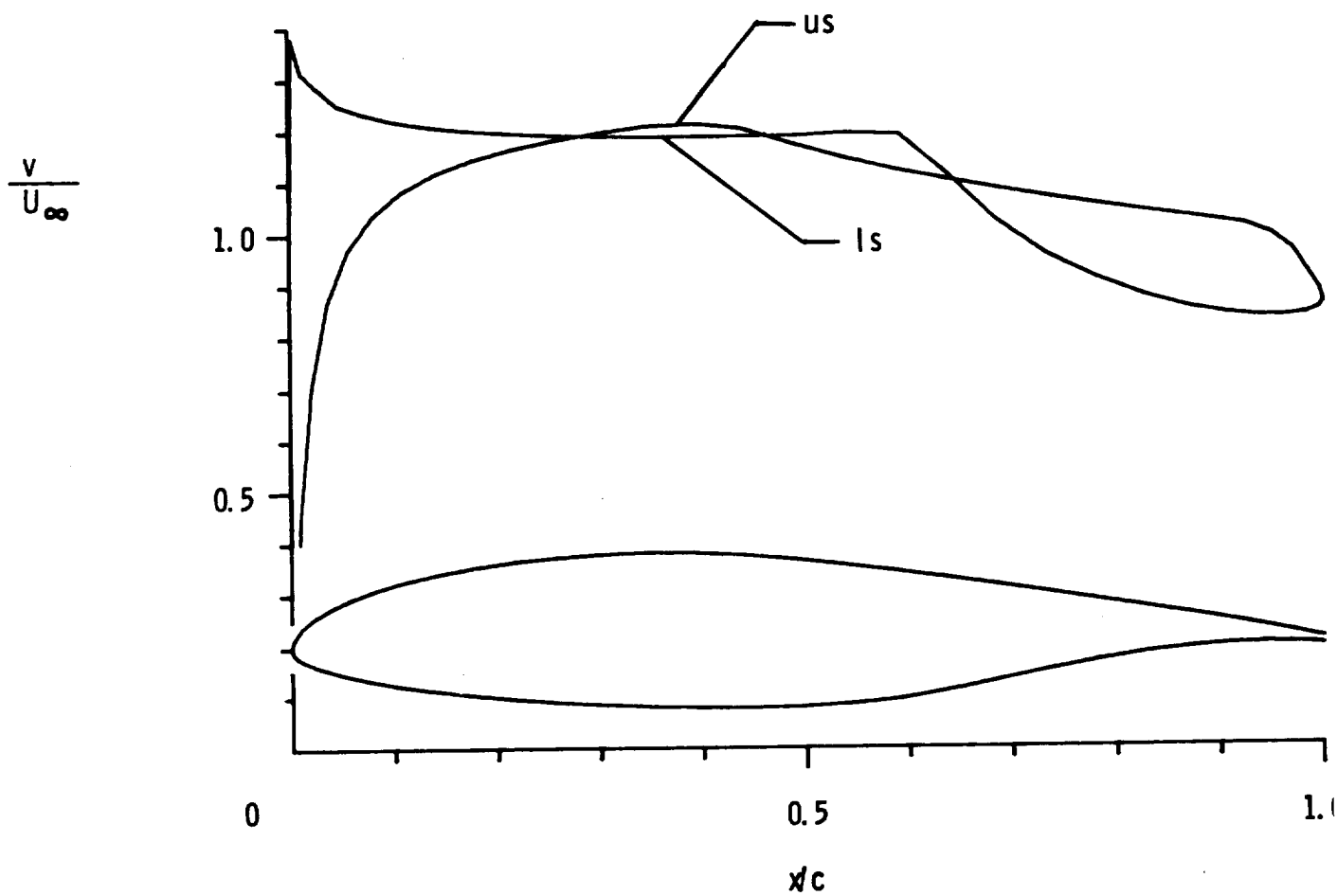
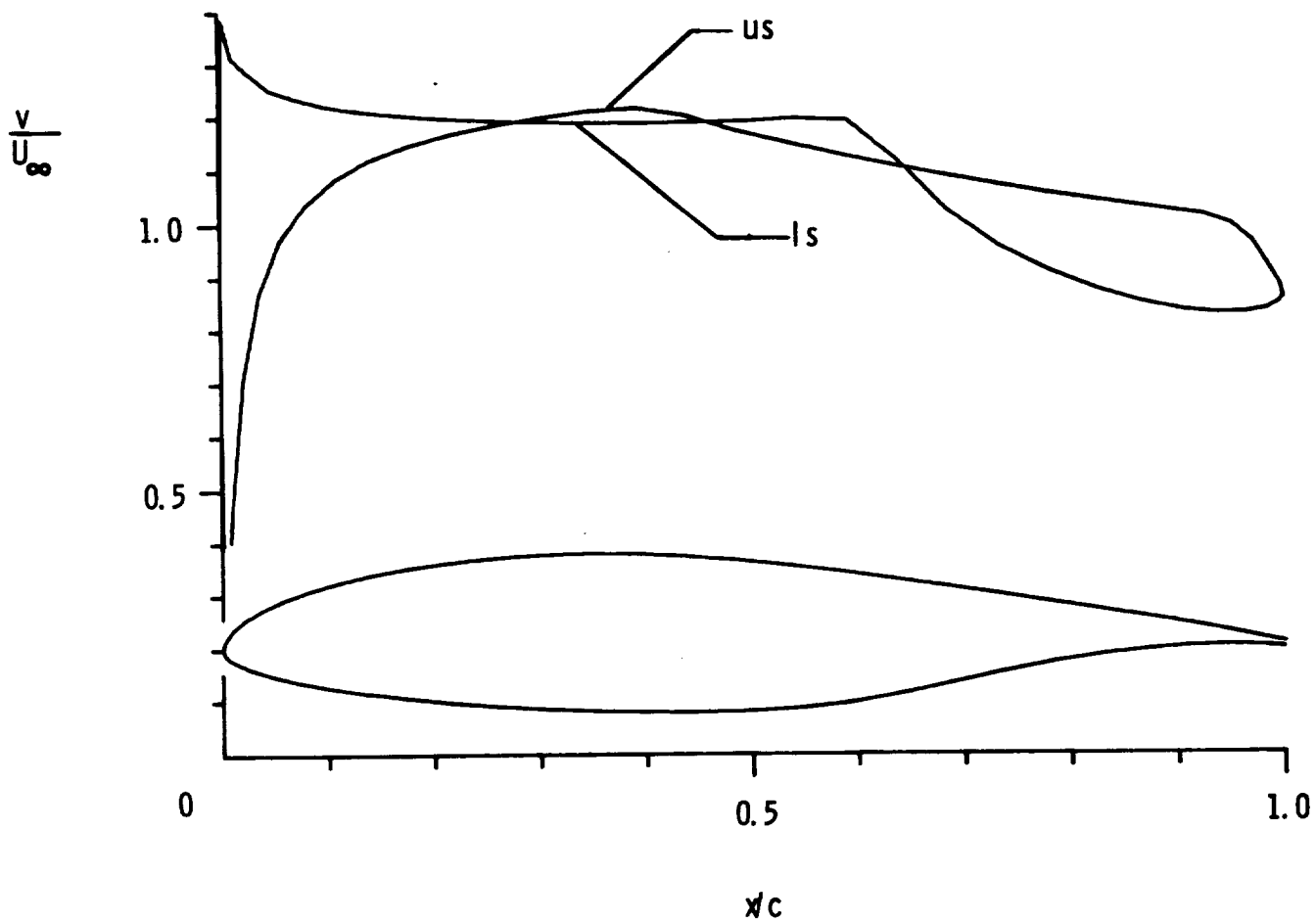


Figure 2. - Diagram without boundary-layer displacement iteration.  
 (  $\alpha = 0^\circ - 9^\circ$  relative to zero-lift line)



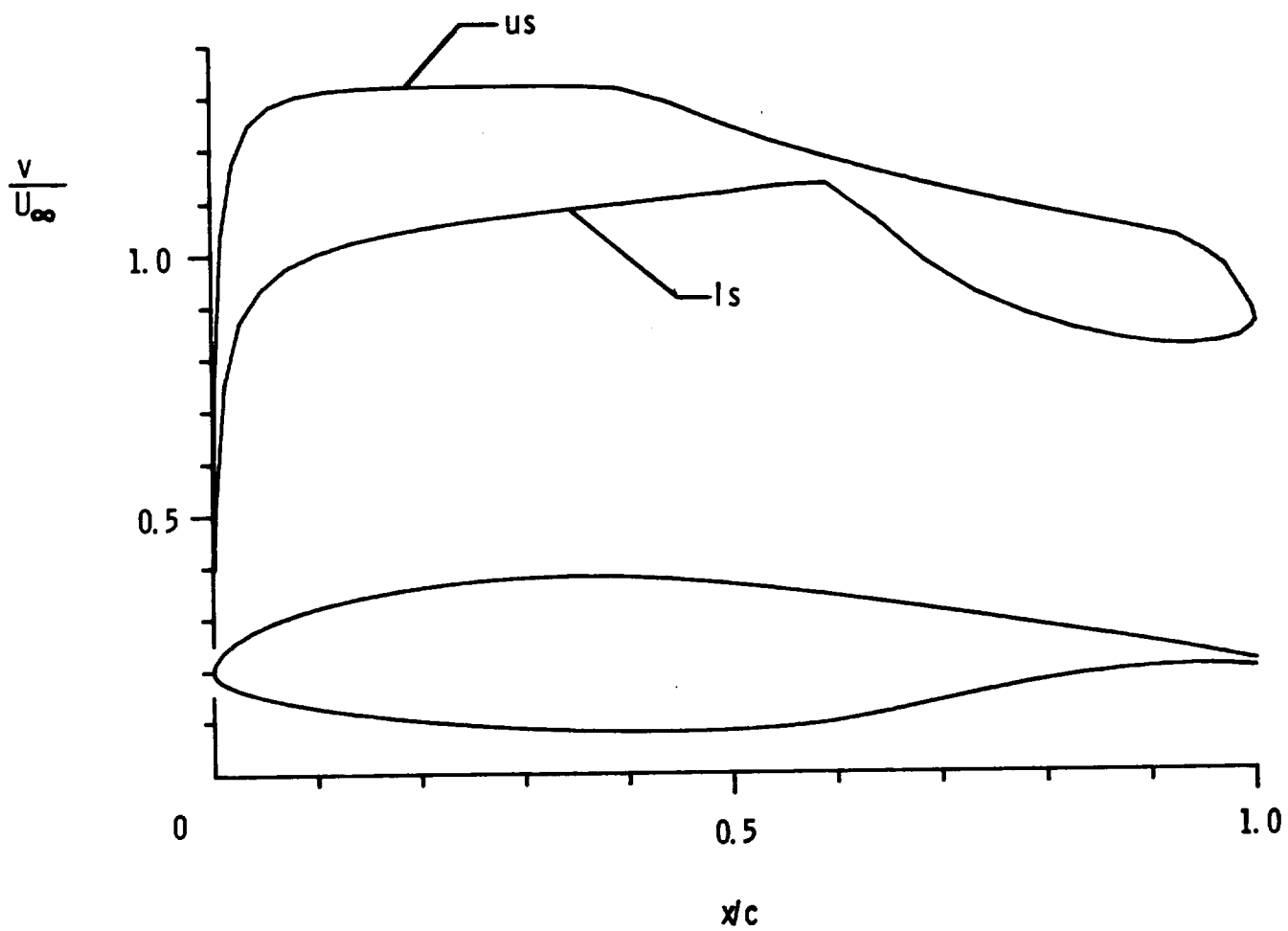
(a)  $\alpha = 0^\circ$ ;  $R = 2 \times 10^6$ .

Figure 3. - Diagram with boundary-layer displacement iteration.  
 ( $\alpha$  relative to zero-lift line)



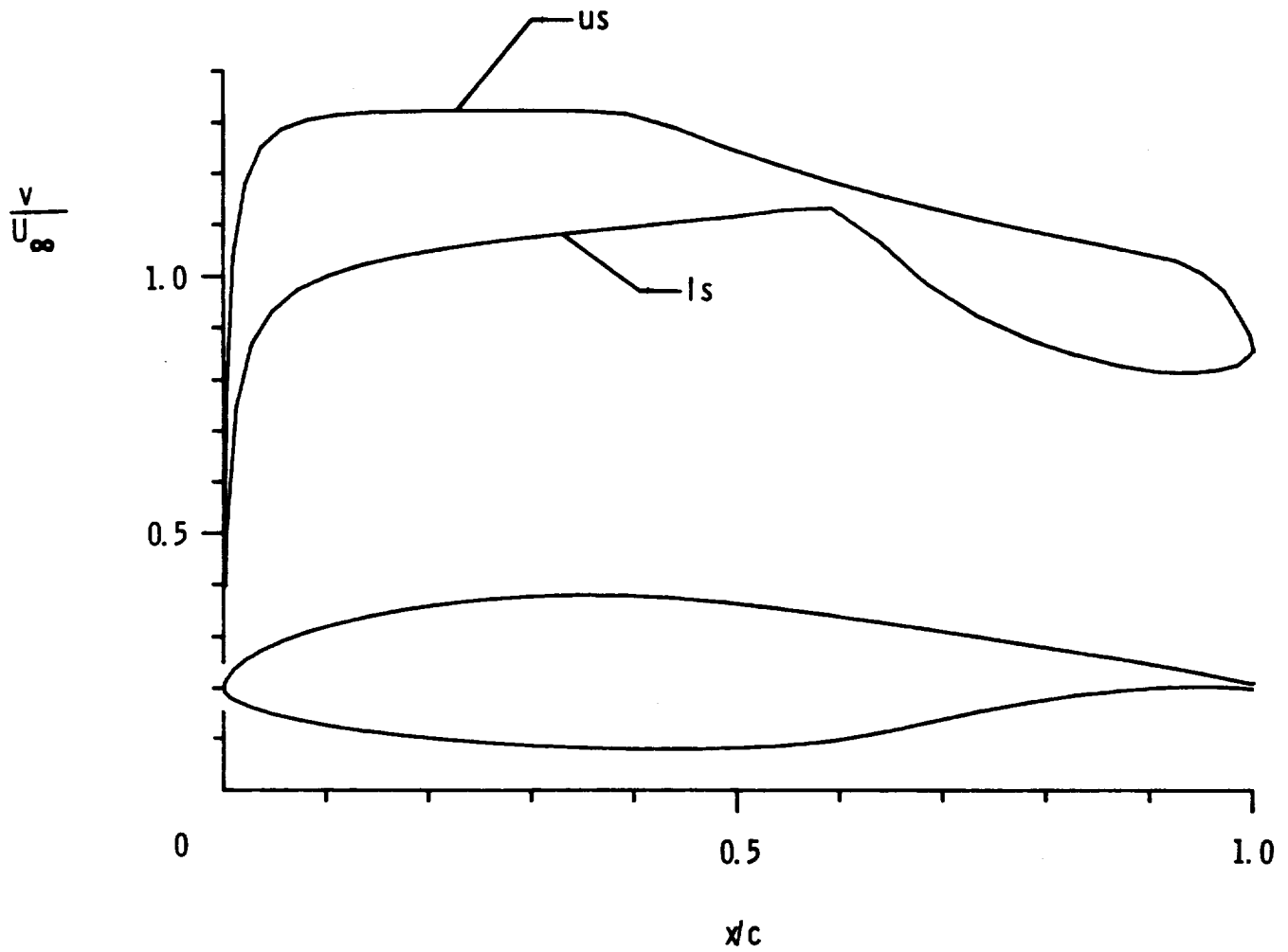
(b)  $\alpha = 0^\circ$ ;  $R = 6 \times 10^6$ .

Figure 3. - Continued.



(c)  $\alpha = 4^\circ$ ;  $R = 2 \times 10^6$ .

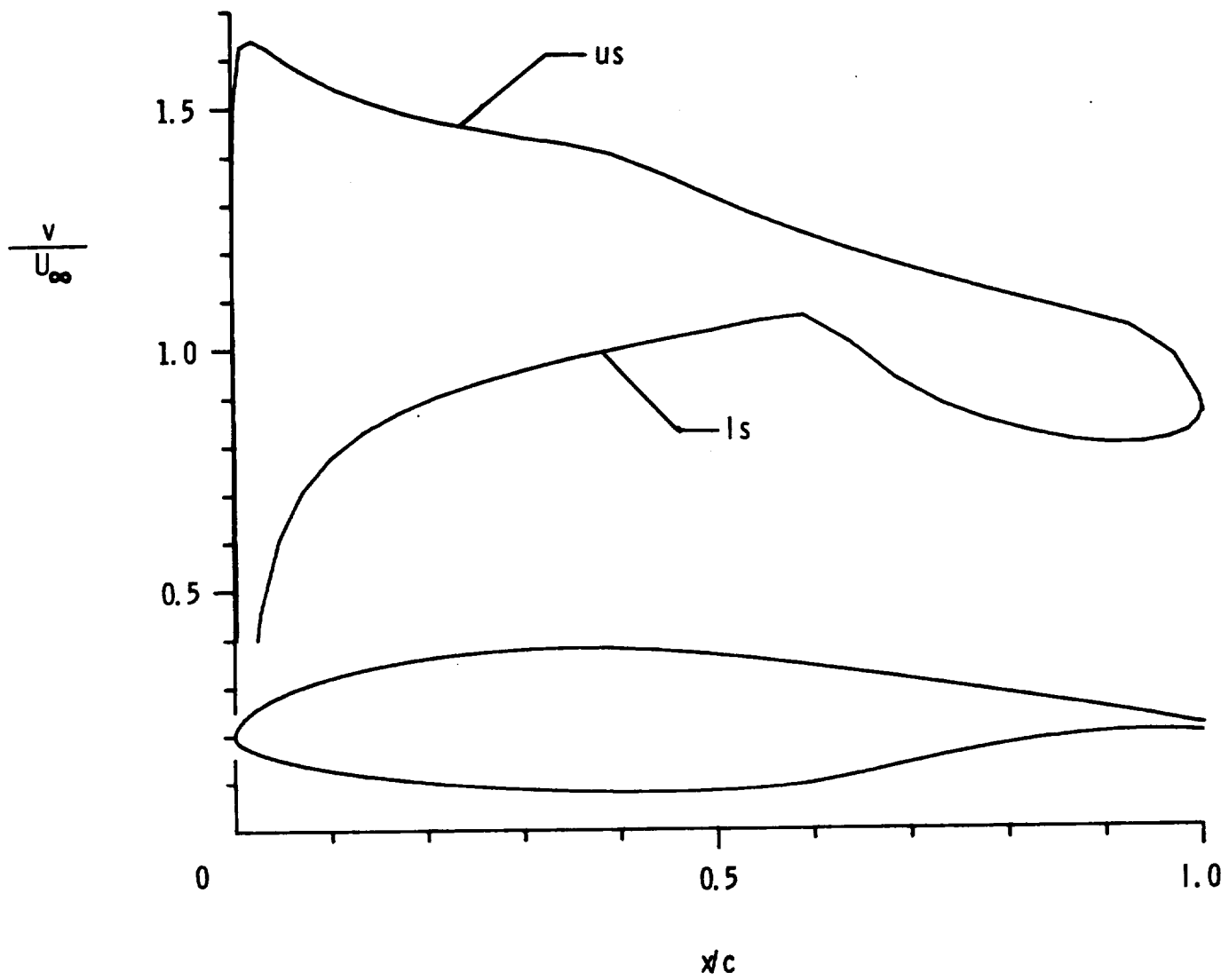
Figure 3. - Continued.



(d)  $\alpha = 4^\circ$ ;  $R = 6 \times 10^6$ .

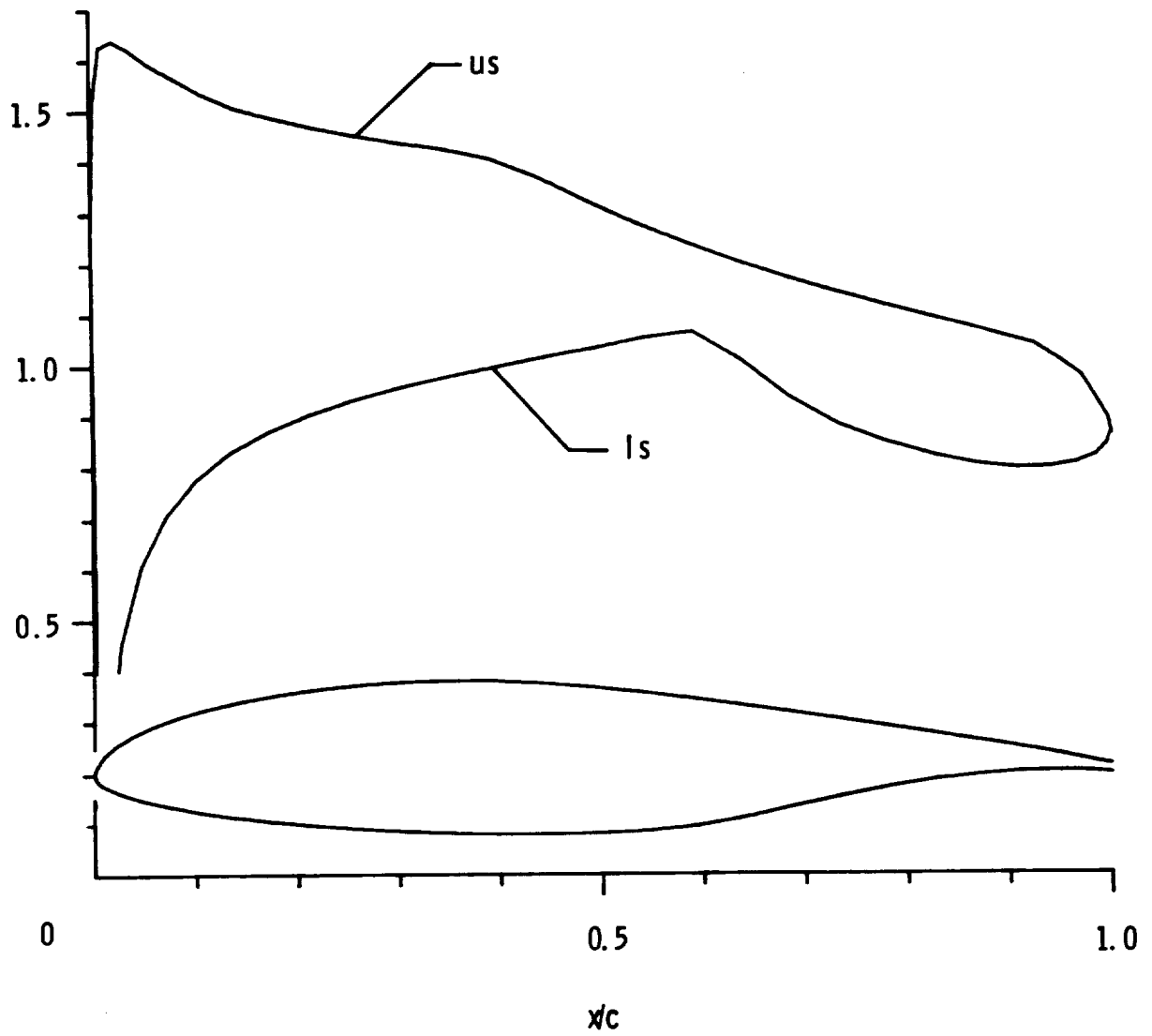
Figure 3. - Continued.





(e)  $\alpha = 8^{\circ}$ ;  $R = 2 \times 10^6$ .

Figure 3. - Continued.



(f)  $\alpha = 8^\circ$ ;  $R = 6 \times 10^6$ .

Figure 3. - Concluded.

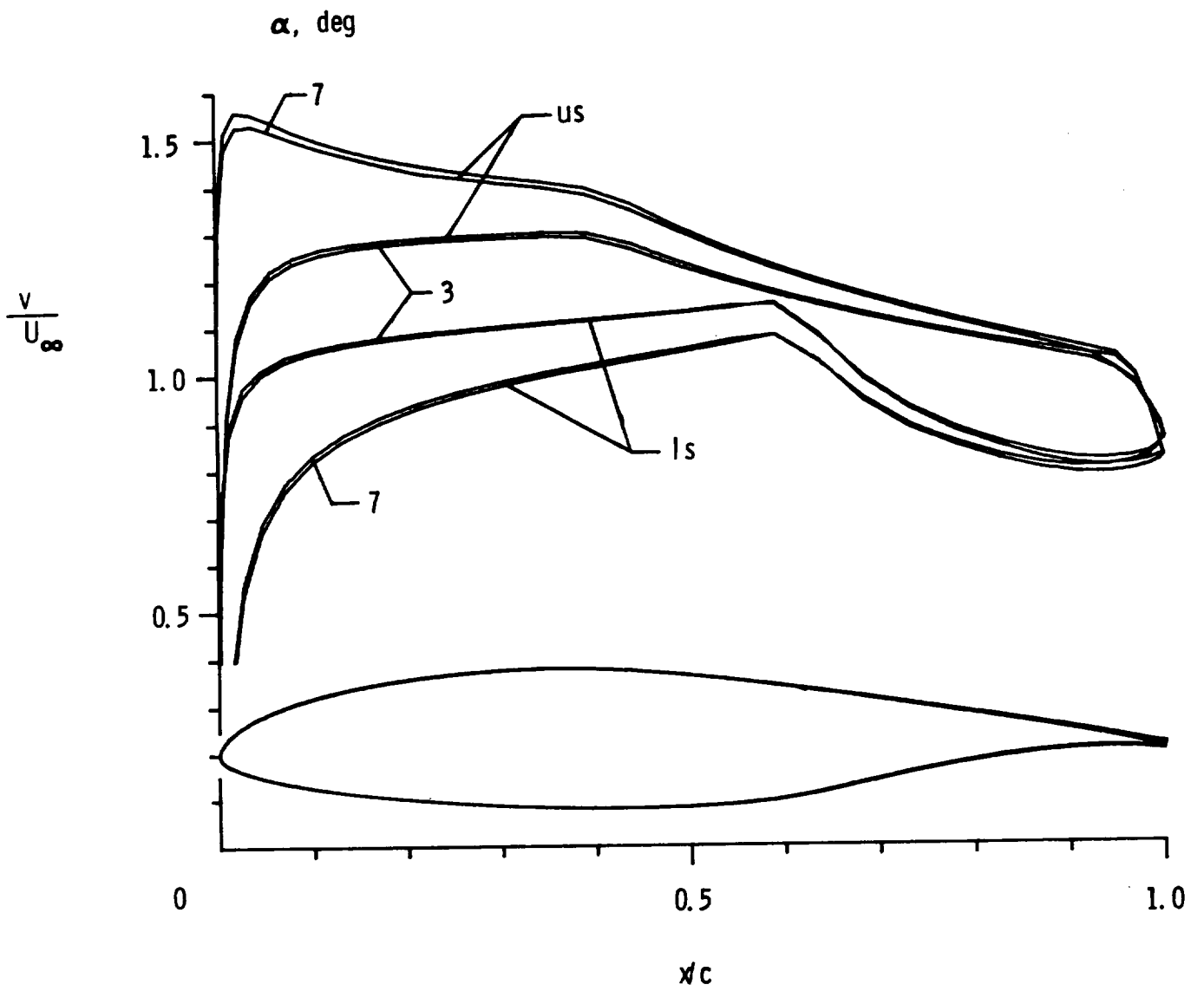


Figure 4. - Diagram with and without boundary-layer displacement iteration.  
 (  $\alpha$  relative to zero-lift line)

